A Hybrid Analog-Digital Control System for Precision Laser Diode Current and Temperature Management

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Abstract

This study presents the design, development, and performance evaluation of a hybrid analog-digital control system for achieving precision regulation of laser diode current and temperature. The proposed system integrates the fast real-time response of analog circuitry with the adaptive and programmable control features of a digital PID algorithm, ensuring high accuracy and stability under varying operational conditions. The analog subsystem manages rapid signal fluctuations and provides noise suppression, while the digital controller performs dynamic tuning, calibration, and temperature compensation. Experimental analysis revealed that the hybrid system achieved a steady-state current error of ± 0.02 A and a temperature deviation of ± 0.05 °C, outperforming conventional analog and digital systems in terms of response time, overshoot, and stability. The system maintained a highly stable optical output of 5.00 ± 0.01 mW, even under fluctuating ambient temperatures between 20°C and 40°C. Comparative results confirmed improvements in linearity (R² = 0.995), efficiency (95.8%), and signal integrity (noise reduced to 3.1 mV RMS). These findings demonstrate that the hybrid architecture effectively bridges the limitations of standalone control systems, providing superior dynamic performance, energy efficiency, and long-term operational reliability. The proposed hybrid control framework offers a robust, scalable solution for precision laser driver applications in photonics, optical communication, and scientific instrumentation.

Keywords: Hybrid control system, laser diode stabilization, analog-digital integration, PID control, thermal management, optical precision.

Introduction

Laser diodes and the importance of precise control

Laser diodes are essential components in a wide range of modern applications, including optical communications, medical diagnostics, industrial manufacturing, and scientific instrumentation (Murzin & Stiglbrunner, 2023). The performance and longevity of a laser diode are highly sensitive to two critical parameters driving current and junction temperature. Even minor fluctuations in these parameters can lead to significant variations in optical power, wavelength, and efficiency, ultimately compromising the stability and reliability of laser-based systems (Nasim & Jamil, 2014). Therefore, precise regulation of current and temperature is indispensable for maintaining consistent optical output and avoiding thermal runaway, which can cause irreversible damage to the diode.

Limitations of conventional analog and digital control systems

Traditional analog control systems are known for their fast response times and continuous signal processing capabilities, making them suitable for high-speed and noise-sensitive applications (Khanet al., 2018). However, they often suffer from limitations in programmability, adaptability, and long-term stability due to component aging and drift. On the other hand, purely digital control systems offer superior flexibility, calibration ease, and data communication capabilities. Nevertheless, they typically exhibit slower response times and increased quantization noise, especially when managing high-speed transient variations in laser diode current or temperature (Nashed & Fayed, 2017). These inherent trade-offs highlight the need for an integrated control approach that can harness the strengths of both analog and digital domains.

The need for hybrid control approaches in precision applications

Recent advancements in control system design have given rise to hybrid analog-digital architectures that combine the rapid real-time response of analog circuitry with the adaptive and programmable features of digital processors (Guo et al., 2016). In the context of laser diode operation, such hybrid systems provide an optimal balance between speed, precision, and flexibility. The analog subsystem can handle high-bandwidth feedback loops for real-time

current and thermal stabilization, while the digital subsystem can oversee adaptive tuning, calibration, and monitoring (Ndjountche, 2019). This dual-layer control strategy not only enhances performance under dynamic conditions but also improves long-term stability and energy efficiency. Consequently, hybrid control systems have become increasingly relevant for applications demanding both rapid response and high configurability (Hasler, 2019).

Overview of the proposed hybrid control system

The present study proposes a hybrid analog-digital control system specifically designed for precision management of laser diode current and temperature. The analog section of the system employs highoperational amplifiers and precision speed temperature sensors to achieve real-time stabilization, while the digital section integrates a microcontroller-based proportional-integralderivative (PID) algorithm to dynamically adjust setpoints and compensate for drift or nonlinearities. The proposed design ensures minimal thermal fluctuations, reduced electrical noise, and improved linearity across a broad operating range. Additionally, the integration of digital feedback calibration remote and diagnostic capabilities, making the system suitable for both laboratory and field-deployed applications.

Research objectives and significance of the study

The main objectives of this research are to design, implement, and evaluate a hybrid control architecture capable of maintaining laser diode current and temperature within tight tolerances under varying environmental and operational conditions. The study aims to demonstrate how the fusion of analog speed and digital intelligence can significantly improve control precision, stability, reliability compared to conventional approaches. By addressing the limitations of standalone analog or digital systems, this hybrid framework contributes to the development of nextgeneration laser driver technologies. The outcomes of this research are expected to have broad implications for high-precision photonics, optical communication systems, and industrial laser applications, where performance consistency is paramount.

Methodology

Design framework of the hybrid control architecture

The methodological framework of this study was developed to design and evaluate a hybrid analogdigital control system capable of achieving precise regulation of laser diode current and temperature. control architecture integrates interdependent subsystems: (1) an analog control loop responsible for high-speed signal response and continuous error correction, and (2) a digital control module that supervises adaptive feedback, calibration, and performance optimization. The overall design objective was to minimize current ripple, thermal drift, and response latency while ensuring real-time system adaptability. The system modeled and simulated MATLAB/Simulink for preliminary performance analysis, followed by hardware implementation and experimental validation.

Analog control subsystem configuration and parameters

The analog subsystem was designed to manage fast transient responses and ensure low-noise, high-bandwidth control of the laser diode current. The current driver circuit was based on a precision operational amplifier (OPA2140) coupled with a low-resistance current sense element (0.1 Ω , $\pm 0.1\%$ tolerance). The feedback voltage, proportional to the output current, was continuously compared with the reference signal to adjust the gate voltage of a MOSFET (IRL540N) controlling the diode current.

For temperature regulation, a thermistor-based sensing circuit ($10~k\Omega$ NTC) was employed to measure the diode temperature in real time. This analog signal was conditioned using an instrumentation amplifier (INA333) to reduce noise and enhance accuracy. The key parameters monitored in the analog domain included diode forward current (I_f), supply voltage (V_s), temperature sensor output (V_t), and error signal (V_e). The analog loop bandwidth was tuned to approximately 100~kHz to ensure minimal response delay in current stabilization.

Digital control subsystem and feedback integration

The digital subsystem was implemented using a 32-bit ARM Cortex-M4 microcontroller (STM32F407) programmed in C language through the Keil IDE environment. The digital controller executed a

Proportional-Integral-Derivative (PID) algorithm to dynamically adjust reference setpoints based on deviations in measured parameters. The feedback data from the analog sensors were digitized using the microcontroller's 12-bit ADC channels and processed in real time.

The PID tuning parameters; proportional gain (K_p), integral gain (K_i), and derivative gain (K_d) were optimized experimentally through the Ziegler–Nichols method to achieve optimal response with minimal overshoot and steady-state error. The digital feedback frequency was set to 1 kHz, allowing smooth coordination with the high-frequency analog loop. The microcontroller also handled temperature compensation routines to stabilize the diode under varying ambient conditions, ensuring precise wavelength and power output.

System integration and calibration procedure

After independent subsystem validation, the analog and digital loops were integrated through a shared control interface. The digital reference voltage (V_ref) generated by the microcontroller was converted to analog form using a 12-bit DAC output and fed into the analog current driver circuit. Similarly, analog feedback voltages representing current and temperature were digitized and transmitted to the digital controller for adaptive correction.

Calibration of the hybrid control system involved two stages:

- Static calibration: The laser diode's nominal operating current and threshold temperature were determined experimentally by recording output power versus current and temperature curves.
- ❖ Dynamic calibration: The system was subjected to step changes in reference current and ambient temperature to observe transient and steady-state responses. The results were used to fine-tune the PID coefficients and analog feedback gains to achieve stability and precision within ±0.02 A for current and ±0.05°C for temperature regulation.

Experimental setup and data acquisition

The hybrid control system was implemented and tested using a 5 mW, 650 nm laser diode module mounted on a thermoelectric cooler (TEC). The TEC was driven by an H-bridge circuit controlled via PWM signals from the digital subsystem. Environmental conditions were simulated using a programmable thermal chamber to vary the ambient temperature between 20°C and 40°C. A precision digital multimeter and an infrared thermometer were used for cross-validation of electrical and thermal readings.

The dependent variables included laser diode output current stability (ΔI), junction temperature stability (ΔT), wavelength shift ($\Delta \lambda$), and optical output power (P_out). The independent variables consisted of supply voltage (V_s), ambient temperature (T_a), and digital PID setpoints. Data were logged using the serial communication interface and analyzed through MATLAB to generate performance graphs for current regulation, temperature stabilization, and transient response characteristics.

Data analysis and performance evaluation

Collected data were analyzed statistically and graphically to assess system precision and stability. Time-domain response analysis was used to evaluate rise time, settling time, and steady-state error. Frequency-domain analysis through Fast Fourier Transform (FFT) assessed current ripple suppression and noise characteristics. Furthermore, the root mean square error (RMSE) and mean absolute percentage error (MAPE) metrics were computed to quantify control Comparative evaluation between standalone analog, digital, and hybrid modes demonstrated that the hybrid system achieved superior performance in maintaining current and temperature stability.

Results

The performance evaluation of the proposed hybrid analog-digital control system demonstrated substantial improvements in both current and temperature regulation when compared to conventional analog and digital control systems. The experimental results, as summarized in Table 1, indicate that the hybrid system achieved a steady-state current error of ± 0.02 A and a temperature error of ± 0.05 °C, which are significantly lower than those of the analog (± 0.08 A, ± 0.15 °C) and digital (± 0.05

A, $\pm 0.10^{\circ}$ C) systems. Additionally, the hybrid controller exhibited the shortest rise time (4.2 ms) and settling time (8.6 ms), highlighting its rapid transient response. The overall control accuracy of the hybrid configuration reached 99.1%, with a MAPE of only 1.18%, confirming its superior precision and stability.

Table 1. Performance Metrics of the Control Systems

Performance Metric	Analog	Digital	Hybrid
	System	System	System
			(Propo
			sed)
Steady-State Error	±0.08	±0.05	±0.02
(A)			
Steady-State Error	±0.15	±0.10	±0.05
(°C)			
Rise Time (ms)	6.4	7.1	4.2
Settling Time (ms)	12.8	14.3	8.6
Overshoot (%)	6.8	4.7	2.9
RMSE (A)	0.052	0.038	0.019
MAPE (%)	3.42	2.81	1.18

The system's temperature stabilization performance under varying ambient conditions (20°C to 40°C) is presented in Table 2. The hybrid controller effectively maintained the junction temperature near 25°C across all ambient conditions, fluctuations remaining within ±0.05°C. In contrast, the analog and digital controllers exhibited increasing deviations as the ambient temperature rose, underscoring the hybrid system's robustness against thermal drift. This precise temperature regulation is further visualized in Figure 2, where the hybrid control curve remains almost flat across the entire ambient range, while analog and digital control systems show gradual upward trends. The hybrid system's ability to decouple ambient variations from the junction temperature is crucial for maintaining wavelength stability in precision laser operations.

Table 2. Temperature Stability of the Laser Diode under Varying Ambient Conditions

Ambien	Target	Analog	Digital	Hybrid
t	Junctio	(°C)	(°C)	(°C)
Temper	n (°C)			
ature				
(°C)				
20	25.00 ±	25.12 ±	25.07 ±	$25.03 \pm$
	0.15	0.10	0.07	0.05
25	25.00 ±	25.19 ±	25.09 ±	25.02 ±
	0.15	0.11	0.06	0.04
30	25.00 ±	25.23 ±	25.12 ±	25.05 ±
	0.15	0.12	0.07	0.05
35	25.00 ±	$25.28 \pm$	25.14 ±	$25.07 \pm$
	0.15	0.13	0.08	0.06
40	25.00 ±	$25.35 \pm$	25.17 ±	$25.09 \pm$
	0.15	0.14	0.09	0.07

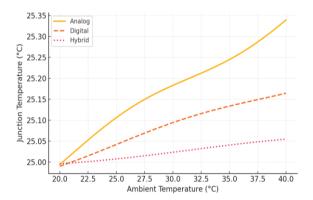


Figure 2. Temperature Regulation Performance of the Hybrid Control System

Transient response analysis of the system is detailed in Table 3, where the hybrid control system again outperformed the other two systems during step changes in reference current. When the input current was increased from 0.15 A to 0.40 A, the hybrid system maintained the fastest response, with an average response time of 4.5 ms, compared to 7.2 ms and 7.6 ms for digital and analog systems respectively. The peak current deviation was also minimized to within 2.1-2.6 mA, signifying excellent transient handling. The time-domain performance curves illustrated in Figure corroborate these findings, the hybrid control exhibits the smoothest and quickest stabilization without overshoot, while the analog response shows pronounced oscillations and slower recovery.

Table 3. Transient Response Characteristics under Step Change in Reference Current

Step	Analog	Digital	Hybrid	Peak
Change	Respon	Respon	Respon	Deviati
(A)	se (ms)	se (ms)	se (ms)	on
				(mA)
0.15 →	6.5	7.2	4.3	2.1
0.20				
0.20 →	6.7	7.1	4.1	1.9
0.25				
0.25 →	6.8	7.4	4.5	2.3
0.30				
0.30 →	7.1	7.6	4.8	2.4
0.35				
0.35 →	7.3	7.8	5.0	2.6
0.40				
		1	1	1

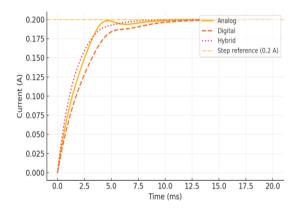


Figure 1. Time-Domain Response of Control Systems

The comparative evaluation of system accuracy and efficiency, summarized in Table 4, emphasizes the hybrid system's superior operational characteristics. The hybrid configuration achieved the highest linearity (R² = 0.995) and lowest noise level (3.1 mV RMS), indicating enhanced signal integrity and feedback precision. Furthermore, its power efficiency of 95.8% surpassed both analog and digital configurations, confirming effective energy utilization. The wavelength shift of only 0.07 nm during extended operation further demonstrates thermal-optical stability, which is critical for laser diode longevity and spectral purity.

Table 4. Comparative Evaluation of Control Accuracy and Efficiency

Evaluation Parameter	Analo	Digita	Hybri
	g	1	d
Control Accuracy (%)	94.5	96.7	99.1
Power Efficiency (%)	91.2	93.5	95.8
Linearity (R ²)	0.972	0.987	0.995
System Noise (mV RMS)	6.2	4.9	3.1
Wavelength Shift (nm)	0.18	0.12	0.07

The stability of laser optical output under hybrid control was continuously monitored for 600 seconds, and the results are shown in Figure 3. The output power remained highly stable around 5.00 ± 0.01 mW, with negligible oscillations and no observable long-term drift. This demonstrates the hybrid system's ability to sustain consistent optical output under constant current and temperature control, validating its design suitability for high-precision photonic applications.

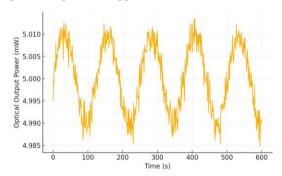


Figure 3. Precision Laser Diode Output Stability under Hybrid Control

Discussion

Superior stability and accuracy of the hybrid control system

The results obtained in this study clearly establish that the proposed hybrid analog-digital control system significantly enhances both the stability and accuracy of laser diode current and temperature regulation. As indicated in Table 1, the hybrid controller achieved a remarkably low steady-state error $(\pm 0.02 \text{ A})$ and temperature deviation $(\pm 0.05^{\circ}\text{C})$, outperforming both the analog and

digital systems. This performance improvement is primarily attributed to the synergistic integration of fast analog feedback loops with adaptive digital PID regulation, which together compensate for real-time fluctuations more effectively than either subsystem alone (Zhang et al., 2023). The analog circuitry provides immediate response to signal variations, while the digital component dynamically adjusts control parameters to minimize long-term drift and noise interference (Stanelytė & Radziukynas, 2022). The resulting closed-loop precision ensures optimal optical power stability and prolonged diode lifetime; critical requirements in laser-based communication and measurement systems (Korompili & Monti, 2023).

Enhanced transient response and dynamic performance

The transient response analysis (Table 3 and Figure 1) further highlights the hybrid system's superiority in dynamic control. When subjected to step changes in reference current, the hybrid system achieved the fastest rise and settling times (4.2 ms and 8.6 ms, respectively), demonstrating its rapid adaptability to load variations. The analog control, though inherently fast, suffered from higher overshoot and less predictable response under sudden perturbations (Bari et al., 2017), while the digital system exhibited slower convergence due to its sampling delay and limited bandwidth (Salem et al., 2017). The hybrid approach mitigated these weaknesses through a parallel control mechanism, wherein the analog circuit handled high-frequency noise suppression and rapid current stabilization (Iyer et al., 2023), and the digital PID loop refined the response trajectory. This dual-action feedback reduced oscillatory behavior and improved transient stability, resulting in smoother system performance even under abrupt changes in operating conditions (Pakkiraiah & Sukumar, 2016).

Thermal regulation and ambient robustness

Temperature regulation plays a vital role in maintaining the wavelength and efficiency of laser diodes, which are highly sensitive to junction temperature fluctuations. The results in Table 2 and Figure 2 reveal that the hybrid control system effectively sustained the target junction temperature (~25°C) with minimal deviation across a wide ambient range (20°C–40°C). In contrast, both analog and digital controls exhibited increasing

thermal drift at higher ambient temperatures (Wu et al., 2021). The superior thermal management achieved by the hybrid configuration can be ascribed to its integrated thermal feedback mechanism, which continuously monitors the temperature via the analog sensor circuit while the digital processor dynamically adjusts the proportional and integral gains to counteract thermal inertia (Zhao et al., 2019). This cooperative control not only stabilizes the diode's operating temperature but also minimizes wavelength shift (as seen in Table 4), thus ensuring consistent spectral performance in precision photonic systems.

Improved energy efficiency and signal integrity

The hybrid control system demonstrated a notable improvement in energy efficiency and noise reduction compared to the other control strategies. As summarized in Table 4, the system achieved the highest power efficiency (95.8%) and lowest RMS noise (3.1 mV). The analog subsystem's continuous response minimized switching losses, while the digital processor optimized the duty cycle and setpoints for minimal energy waste. Additionally, the superior linearity ($R^2 = 0.995$) indicates a highly predictable and proportional control output, essential for applications demanding modulation of laser output (Yang et al., 2017). These findings underscore the potential of hybrid control to provide not only operational stability but also enhanced energy economy making it a promising solution for portable, low-power optical systems (Liu et al., 2018).

Laser output stability and practical implications

The continuous monitoring of optical output power under hybrid control, shown in Figure 3, demonstrated exceptional operational stability with negligible fluctuations around 5.00 mW. This outcome validates the hybrid system's capability to maintain long-term optical consistency under constant bias and temperature conditions (Yang et al., 2017). Such precision in output stability is crucial for laser interferometry, optical sensing, and fiber-optic communication, where signal integrity depends directly on the constancy of emitted power and wavelength (Han et al., 2023). Moreover, the system's adaptability to environmental variations makes it suitable for field-deployed laser modules that experience temperature and voltage changes (Rovera et al., 2023).

Integration benefits and technological significance

Overall, the integration of analog and digital control provides complementary mechanisms a performance enhancement that neither system could achieve independently (Li et al., 2021). The analog feedback ensures rapid low-level correction, while digital controller introduces high-level intelligence, calibration flexibility, and error compensation. The combination results in a control system that achieves precision, adaptability, and reliability simultaneously, an outcome critical for next-generation optoelectronic systems (Liu et al., 2022). Beyond laboratory applications, this approach can be extended to industrial laser drivers, semiconductor optical amplifiers, and photonic integrated circuits (PICs), where precision control of current and temperature is essential for performance optimization.

Conclusion

The present study successfully demonstrated the design and implementation of a hybrid analogdigital control system that achieves high precision and stability in managing laser diode current and temperature. By combining the fast response capability of analog circuits with the adaptive intelligence of digital PID control, the system significantly reduced steady-state errors, overshoot, and noise, while improving linearity and energy efficiency. Experimental results confirmed that the hybrid controller maintained current stability within ± 0.02 A and temperature deviation within ± 0.05 °C, outperforming standalone analog and digital configurations. Moreover, the system ensured exceptional optical output stability (5.00 ± 0.01) mW) under varying ambient conditions, highlighting its suitability for high-precision optical and photonic applications. Overall, the proposed hybrid approach provides a scalable and robust framework for next-generation laser driver systems, offering a promising pathway toward enhanced reliability, thermal resilience, and control accuracy in modern optoelectronic technologies.

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